

# Group Theory for Physicists

## Lecture Notes

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## Preliminaries

### Dates:

Five Mondays 28.04.25, 05.05.25, 12.05.25, 19.05.25, 26.05.22, 02.06.25

Lecture 9 - 12, Tutorial 14 - 16, Homework Problems

Test TBD

Script and other details are available on StudOn and at

<https://www.eso.org/~gjunker/VorlesungSS2025.html>

### Literature:

Any group theory textbook will cover most of the topics. Some elementary ones are

- W. Lucha and F.F. Schöberl, *Gruppentheorie* (BI, 1993)
- H.F. Jones, *Groups, Representations and Physics* 2nd Ed. (Taylor & Francis, 1998)
- E. Stiefel and A. Fässler, *Gruppentheoretische Methoden und ihre Anwendung* (Teuber, 1979)
- ...

### Group theory:

Is the mathematical tool to describe symmetries, for example, in physical systems. Thus group theory and the closely related representation theory have many important applications in physics, chemistry, and materials science.

### Aim of lecture:

Present the basic concepts of group theory enabling us to utilise symmetries of physical systems to analyse their properties.

Here focus on quantum mechanics and statistical physics.

# 1 Basic Terms and Definitions

## 1.1 Definition of an Abstract Group

Definition: A *group*  $G$ , or better  $(G, \circ)$ , is a set of elements (finite or infinite in number),

$$G = \{g_1, g_2, \dots\} \quad \text{or} \quad G = \{g(\alpha) | \alpha \in I\}, \quad I = \text{index set}$$

with a *composition law* (group multiplication)

$$\circ : \begin{array}{l} G \times G \rightarrow G \\ (g_1, g_2) \mapsto g_1 \circ g_2 \end{array}$$

satisfying below conditions

1. *Associative Law:*

$$g_1 \circ (g_2 \circ g_3) = (g_1 \circ g_2) \circ g_3 = g_1 \circ g_2 \circ g_3$$

2. *Unit Element:*  $\exists e \in G$  such that

$$e \circ g = g \circ e = g \quad \forall g \in G$$

3. *Inverse Element:*  $\forall g \in G \exists g^{-1} \in G$  such that

$$g^{-1} \circ g = e = g \circ g^{-1}$$

**Remarks:**

- In general  $g_1 \circ g_2 \neq g_2 \circ g_1$ , that is, the group multiplication is *not commutative*  $\Leftrightarrow$ : *non-abelian group*
- *Abelian group*  $\Leftrightarrow g_1 \circ g_2 = g_2 \circ g_1 \quad \forall g_1, g_2 \in G$
- *Order of a group:* Number of (inequivalent) elements

$$g = \{g_1, g_2, \dots, g_n\} \quad \Rightarrow \quad \text{ord } G = n$$

- *Finite group*  $\Leftrightarrow \text{ord } G < \infty$
- *Discrete group:* Countable infinite number of elements
- *Continuous group* uncountable number of elements

$$g = g(\alpha), \quad \alpha \in I \quad \text{index set}$$

**Conclusions from definition:**

- $g_1 \circ g = g_2 \circ g \quad \Rightarrow \quad g_1 = g_2$
- $g \circ g_1 = g \circ g_2 \quad \Rightarrow \quad g_1 = g_2$
- $e$  and  $g^{-1}$  are unique
- $(g^{-1})^{-1} = g \quad (g_1 \circ g_2)^{-1} = g_2^{-1} \circ g_1^{-1}$
- $g_1 \circ g = g_2$  and  $g \circ g_1 = g_2$  have solutions  $g = g_1^{-1} \circ g_2$  and  $g = g_2 \circ g_1^{-1}$ , respectively.

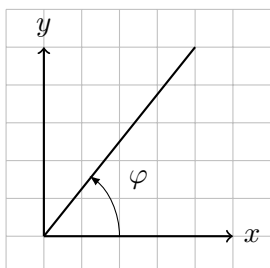
**Notation:** From now on

$$g_1 \circ g_2 = g_1 g_2 \quad \underbrace{g \circ g \circ \dots \circ g}_{n\text{-times}} =: g^n$$

## Examples:

### Abelian Groups

- *Trivial group*:  $E = \{e\}$ ,  $\text{ord } E = 1$
- *Reflection group*:  $C_2 = \{e, \sigma\}$  with  $\sigma^2 = e$ ,  $\text{ord } C_2 = 2$
- $Z_n = \{0, 1, 2, \dots, n-1\}$ ,  $\circ = \text{addition mod } n$ ,  $\text{ord } Z_n = n$
- $(\mathbb{Z}, +)$  and  $(\mathbb{R}^+, \cdot)$ , both are of infinite order
- Rotation in plane by angle  $\varphi \in I = [0, 2\pi[$



### Non-abelian Groups

- $GL(n, K)$ : Set of invertible  $n \times n$  matrices over field  $K$ ,  $\circ = \text{matrix multiplication}$
- $S_n$ : Group of permutations of  $n$  objects,  $\text{ord } S_n = n!$

## 1.2 Group Structures

### 1.2.1 Subgroups

Definition: A subset  $H \subset G$  is called a *subgroup* of  $G$  if the group multiplication of  $G$  restricted on the subset  $H$  is closed, i.e.  $\circ : H \times H \rightarrow H$

- $(\{e\}, \circ)$  and  $(G, \circ)$  are *trivial* subgroups
- Non-trivial subgroups  $\Leftrightarrow$  *proper* subgroups

### 1.2.2 Conjugation and Conjugacy Classes

Definition: Two elements  $g_1, g_2 \in G$  are *conjugate* to each other if

$$\exists g \in G \quad \text{such that} \quad g_1 = g g_2 g^{-1}$$

Conjugation is *transitive*: 
$$\begin{aligned} g_1 &= g g_2 g^{-1} \\ g_2 &= h g_3 h^{-1} \end{aligned} \Rightarrow g_1 = k g_3 k^{-1}$$

Proof:  $g_3 = h^{-1} g_2 h = h^{-1} g^{-1} g_1 g h = k g_1 k^{-1}$  with  $k = (gh)^{-1}$

Definition: The set of all conjugate elements is called *conjugacy class* or simply class

#### Remarks:

- A class is uniquely defined by one of its elements say  $a$

$$\{g_1 a g_1^{-1}, g_2 a g_2^{-1}, \dots, g_n a g_n^{-1}\} \quad \text{for} \quad \text{ord } G = n$$

- $\{e\}$  is a class by itself
- Each element  $g \in G$  belongs exactly to one class  $\Rightarrow$  disjoint partition of  $G$
- For abelian groups each element forms its own class. Why?

Definition: The *order of a group element* is the smallest integer  $m \in \mathbb{N}$  such that  $g^m = e$ .

**Remarks:**

- All elements within one class have the same order

$$g^m = e \quad \Rightarrow \quad (g_i g g_i^{-1})^m = g_i g \cdots g g_i^{-1} = g_i g^m g_i^{-1} = e$$

- Let  $G$  be a matrix group  $\Rightarrow \text{Tr}(g_i g g_i^{-1}) = \text{Tr } g \Rightarrow$  the trace is constant on a class
- Functions that are constant for members of the same conjugacy class are called class functions.

### 1.2.3 Normal Subgroups (Invariant Subgroups, Self-conjugate Subgroups)

Definition: A subgroup  $N \subset G$  is called *normal subgroup* (or invariant subgroup or self-conjugate subgroup) if

$$\forall n \in N \quad \text{and} \quad \forall g \in G \quad \Rightarrow \quad g n g^{-1} \in N$$

In short

$$g N g^{-1} = N \quad \forall g \in G$$

**Remarks:**

- Normal subgroups consist of classes
- *Simple group:* All its normal subgroups are trivial
- *Semi-Simple group:* All its normal subgroups are abelian

### 1.2.4 Cosets

Let  $H \subset G$  be a subgroup of  $G$  and  $g \in G$  a fixed group element

*Left coset:*  $gH := \{gh | h \in H\}$ , mainly used with terminology coset

*Right coset:*  $Hg := \{hg | h \in H\}$

Left and Right cosets are disjoint partitions of  $G$

In general  $Hg \neq gH$

*Index of  $H$ :* Number of left cosets =  $k$  = Number of right cosets

**Lagrange's Theorem:**

$$\text{ord } H = \frac{1}{k} \text{ord } G, \quad \text{where } k \in \mathbb{N} \text{ is the index of } H$$

Proof: Disjoint partition  $G = \{H, g_1 H, \dots, g_{k-1} H\}$  and  $\text{ord}(g_i H) = \text{ord } H$

**Remark:**  $Hg = gH \quad \forall g \in G \quad \Leftrightarrow \quad H$  is normal subgroup

### 1.2.5 Quotient Group

Let  $N \subset G$  be normal subgroup of  $G$  with index  $k$ .

$$F := \{N, g_1 N, g_2 N, \dots, g_{k-1} N\}$$

is disjoint partition of  $G$  into cosets with respect to  $N$ .

Notation:  $F = G/N$  is *quotient group* with  $\text{ord } F = k$

Proof of group properties:

- Group multiplication:

$$(g_1N)(g_2N) = g_1Ng_2N = g_1g_2g_2^{-1}Ng_2N = g_1g_2NN = g_3N \in F$$

- Neutral element:

$$gN \circ N = gN, \quad N \circ gN = NgN = gg^{-1}NgN = gNN = gN$$

- Inverse element:

$$g^{-1}N \circ gN = NN = N, \quad gN \circ g^{-1}N = gNg^{-1}N = N$$

### 1.3 Group Morphisms

*Group homomorphism:* Let  $(G, \circ)$  and  $(G', \star)$  be two groups. Then the mapping

$$\Phi : \begin{array}{l} G \rightarrow G' \\ g \mapsto \Phi(g) \end{array} \quad \text{with} \quad \Phi(g_1) \star \Phi(g_2) = \Phi(g_1 \circ g_2)$$

is a group homomorphism. In general the mapping is not reversible.

*Group isomorphism:* A homomorphism with bijective mapping  $\Phi$ , that is,

$$\begin{aligned} g_1 \neq g_2 &\Rightarrow \Phi(g_1) \neq \Phi(g_2), \text{ reversible,} \\ &\exists \Phi^{-1} : \begin{array}{l} G' \rightarrow G \\ \Phi(g) \mapsto g \end{array} \end{aligned}$$

*Isomorphic groups:*

$$G_1 \simeq G_2 \quad :\Leftrightarrow \quad \exists \text{ Isomorphism } \Phi : G_1 \rightarrow G_2$$

Isomorphic groups are in essence identical.

Example:  $SO(2) \simeq U(1)$ , rotation in plane  $\simeq$  multiplication of complex number by  $e^{i\phi}$

*Automorphism:* Isomorphism  $G \rightarrow G$

*Inner Automorphism:*

$$\Phi_h : \begin{array}{l} G \rightarrow G \\ g \mapsto \Phi_h(g) := hgh^{-1} \end{array} \quad h \in G \text{ fixed, conjugation}$$

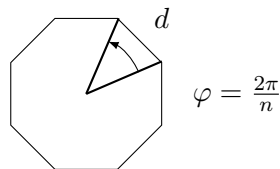
*Outer Automorphism:* all automorphism being not an inner automorphism

## 2 Finite Groups and Representations

### 2.1 Examples of Finite Groups and Properties

#### 2.1.1 The cyclic group $C_n$

Symmetry group of rotations of a regular polygon with  $n$  directed sides



$$C_n := \{e, d, d^2, \dots, d^{n-1}\} \quad \text{with} \quad d^n = e$$

Generator:  $d :=$  rotation by angle  $\varphi = \frac{2\pi}{n}$

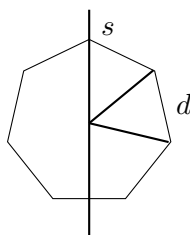
**Generating set of a group:** Set of group elements (generators) which allows to generate all group elements **via products and inverses**. In general this set is not unique.

$C_n$  is abelian and isomorphic to  $Z_n$  (under addition of integers mod  $n$ ):

$$C_n \simeq Z_n \quad \text{as} \quad d^r d^s = d^{r+s} \quad \text{with} \quad r+s = (r+s) \bmod n, \quad \text{ord } C_n = n$$

#### 2.1.2 The dihedral group $D_n$ (Diedergruppe)

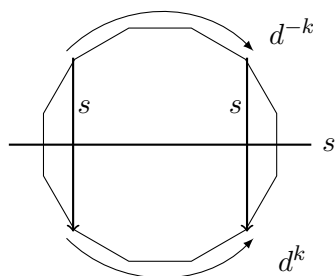
Group of  $n$  rotations  $d$  and reflection  $s$  keeping a regular  $n$ -polygon invariant



Example  $D_8$  : rotations (1st line) and reflections (2nd line)



Generating set:  $\{d, s\}$  with  $d =$  rotation by  $\varphi = \frac{2\pi}{n}$  and  $s =$  reflection on fixed axis  
 $D_n := \{e, d, d^2, \dots, d^{n-1}, s, sd, \dots, sd^{n-1}\}$  with  $d^n = e = s^2$ ,  $d^{-k}s = sd^k$ ,  $d^k s = sd^{-k}$



$$\text{ord } D_n = 2n$$

$$\text{Subgroup } C_n \subset D_n$$

$D_n$  is NOT abelian for  $n > 2$  as  $d^{-1}s = sd \neq sd^{-1}$

### 2.1.3 The permutation group $S_n$

Group of permutations of  $n$  objects

ord  $S_n = n!$

*General element:* Object  $j \rightarrow \pi_j$ , where  $\pi_j \in \{1, 2, \dots, n\}$  and  $\pi_j \neq \pi_k$  for  $j \neq k$

$$P = \begin{pmatrix} 1 & 2 & \cdots & n \\ \pi_1 & \pi_2 & \cdots & \pi_n \end{pmatrix}$$

*Neutral element:*

$$e = \begin{pmatrix} 1 & 2 & \cdots & n \\ 1 & 2 & \cdots & n \end{pmatrix}$$

*Inverse element:*

$$P^{-1} = \begin{pmatrix} \pi_1 & \pi_2 & \cdots & \pi_n \\ 1 & 2 & \cdots & n \end{pmatrix}$$

*Group multiplication:* successive permutation

$$\text{Example: } \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}$$

$$\begin{array}{l} \text{Proof:} \\ 1 \rightarrow 3 \rightarrow 2 \\ 2 \rightarrow 1 \rightarrow 1 \\ 3 \rightarrow 2 \rightarrow 3 \end{array}$$

$$\text{But: } \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}$$

$$\Rightarrow S_n \text{ is NOT abelian for } n \geq 3$$

Exercise: Show that  $S_2 \simeq C_2$

More on permutation group in Tutorial Exercise 1

## 2.2 Cayley or Group Tables

### 2.2.1 Definition

$G$	$g_1$	$g_2$	$\cdots$	$g_i$	$\cdots$	$g_n$
$g_1$	$g_1^2$	$g_1 g_2$	$\cdots$	$g_1 g_i$	$\cdots$	$g_1 g_n$
$g_2$	$g_2 g_1$	$g_2^2$	$\cdots$	$g_2 g_i$	$\cdots$	$g_2 g_n$
$\vdots$			$\ddots$			
$g_i$	$g_i g_1$	$g_i g_2$	$\cdots$	$g_i^2$	$\cdots$	$g_i g_n$
$\vdots$					$\ddots$	
$g_n$	$g_n g_1$	$g_n g_2$		$\cdots$		$g_n^2$

**Remarks:**

- Useful only for finite groups of low order  $n$
- $G$  abelian  $\Leftrightarrow$  group table is symmetric as  $g_i g_j = g_j g_i$
- Isomorphic groups have identical tables

**Examples:**

$$\begin{array}{c|cc} C_2 & e & d \\ \hline e & e & d \\ d & d & e \end{array} \quad \text{recall } d^2 = e$$

$C_3$	$e$	$d$	$d^2$	
$e$	$e$	$d$	$d^2$	recall $d^3 = e$
$d$	$d$	$d^2$	$e$	
$d^2$	$d^2$	$e$	$d$	

## 2.2.2 Cayley's theorem

Theorem: Every finite group  $G$  of order  $n$  is a subgroup of  $S_n$

*Proof:* Obvious as each row in group table corresponds to a rearrangement of group elements.

$$\{gg_1, gg_2, \dots, gg_n\} =: \{g_{\pi_1}, g_{\pi_2}, \dots, g_{\pi_n}\}$$

$$\Rightarrow g \rightarrow P(g) = \begin{pmatrix} 1 & 2 & \cdots & n \\ \pi_1 & \pi_2 & \cdots & \pi_n \end{pmatrix}$$

Corollary: Each row in the group table contains each element of  $G$  exactly once.

Also known as rearrangement theorem.

**Remarks:**

- Number of different (non-isomorphic) groups of order  $n$  is finite
- There exists only ONE group of order 2, the reflection group  $S_2 \simeq C_2 \simeq Z_2$
- $S_3 \simeq D_3$  (obvious as  $\text{ord } S_3 = 6 = \text{ord } D_3$ ) has only ONE subgroup of order 3 isomorphic to  $C_3 \Rightarrow$  There exists only ONE group of order 3.
- $S_4$  has two subgroups of order 4:  $\{C_4, D_2\}$
- Group summation:

$$\sum_{g \in G} f(g) = \sum_{g \in G} f(gh) = \sum_{g \in G} f(hg) = \sum_{g \in G} f(g^{-1})$$

Is valid for all finite groups.

Extension to continuous (unimodular) groups via invariant Haar measure possible.

- Group average: As  $\sum_{g \in G} 1 = \text{ord } G$

$$\langle \cdot \rangle_G := \frac{1}{\text{ord } G} \sum_{g \in G} (\cdot)$$

## 2.2.3 Klein's four group (Kleinsche Vierergruppe $V = D_2$ )

Recall:  $D_2 = \{e, d, s, ds\}$  with  $d^2 = e = s^2$ ,  $d = d^{-1}$ ,  $s = s^{-1}$ ,  $ds = sd$  abelian

$D_2$	$e$	$d$	$s$	$sd$
$e$	$e$	$d$	$s$	$sd$
$d$	$d$	$e$	$sd$	$s$
$s$	$s$	$sd$	$e$	$d$
$sd$	$sd$	$s$	$d$	$e$

**Remarks:**

- $E = \{e\}$  is trivial subgroup
- $e$  on diagonal  $\Leftrightarrow$  each element is its inverse
- To each  $e$  on diagonal exists a subgroup of order 2.  
 $\{e, d\}$ ,  $\{e, s\}$  and  $\{e, sd\}$  are normal subgroups isomorphic to  $C_2$
- Factor group  $D_2/C_2 = C_2$  or  $D_2 = C_2 \otimes C_2$  (direct product of groups in Tutorial)
- Other representation:  $\{1, 3, 5, 7\}$  with group law being multiplication modulo 8



### 2.2.4 The $D_3$ group

Recall:  $D_2 = \{e, d, d^2, s, ds, sd^2\}$  with  $d^3 = e = s^2$ ,  $ds = sd^{-1} = sd^2$ ,  $d^2s = sd^{-2} = sd$

$D_3$	$e$	$d$	$d^2$	$s$	$sd$	$sd^2$
$e$	$e$	$d$	$d^2$	$sd$	$sd$	$sd^2$
$d$	$d$	$d^2$	$e$	$sd^2$	$s$	$sd$
$d^2$	$d^2$	$e$	$d$	$sd$	$sd^2$	$s$
$s$	$s$	$sd$	$sd^2$	$e$	$d$	$d^2$
$sd$	$sd$	$sd^2$	$s$	$d^2$	$e$	$d$
$sd^2$	$sd^2$	$s$	$sd$	$d$	$d^2$	$e$

#### Remarks:

- Subgroups:  $C_3 \subset D_3$ ,  $H_1 := \{e, s\}$ ,  $H_2 := \{e, sd\}$ ,  $H_3 := \{e, sd^2\}$  with  $H_i \simeq C_2$
- Cosets:  $\text{ord } D_3 = 6$ ,  $\text{ord } C_3 = 3$ ,  $\text{ord } C_2 = 2$   
 Lagrange:  $\text{Index } C_2 = 6/2 = 3 \rightarrow 3 \text{ cosets for } C_2 \simeq H_1$   
 3 right cosets of  $H_1$ :  $H_1 = \{e, s\}$ ,  $H_1d = \{d, sd\}$ ,  $H_1d^2 = \{d^2, sd^2\}$   
 3 left cosets of  $H_1$ :  $H_1 = \{e, s\}$ ,  $dH_1 = \{d, ds\}$ ,  $d^2H_1 = \{d^2, d^2s\}$   
 Note:  $dH_1 \neq H_1d$ , it is NOT a normal subgroup  
 2 right cosets of  $C_3$ :  $C_3 = \{e, d, d^2\}$ ,  $C_3s = \{s, ds, d^2s\} = \{s, sd^2, sd\}$   
 2 left cosets of  $C_3$ :  $C_3 = \{e, d, d^2\}$ ,  $sC_3 = \{s, sd, sd^2\}$   
 Note:  $sC_3 = C_3s$ ,  $C_3$  is normal subgroup,  $D_3/C_3 \simeq C_2$
- Quotient group:  $C_2 := \{E, D\}$ , where  $E := \{e, d, d^2\}$ ,  $D := \{s, sd, sd^2\}$   
 $\rightarrow ED = DE$ ,  $D^2 = E$
- Conjugacy classes:  $\{e\}$ ,  $\{d, d^2\}$ ,  $\{s, sd, sd^2\}$  (see Tutorial)

\*\*\* End of Lecture 1 \*\*\*