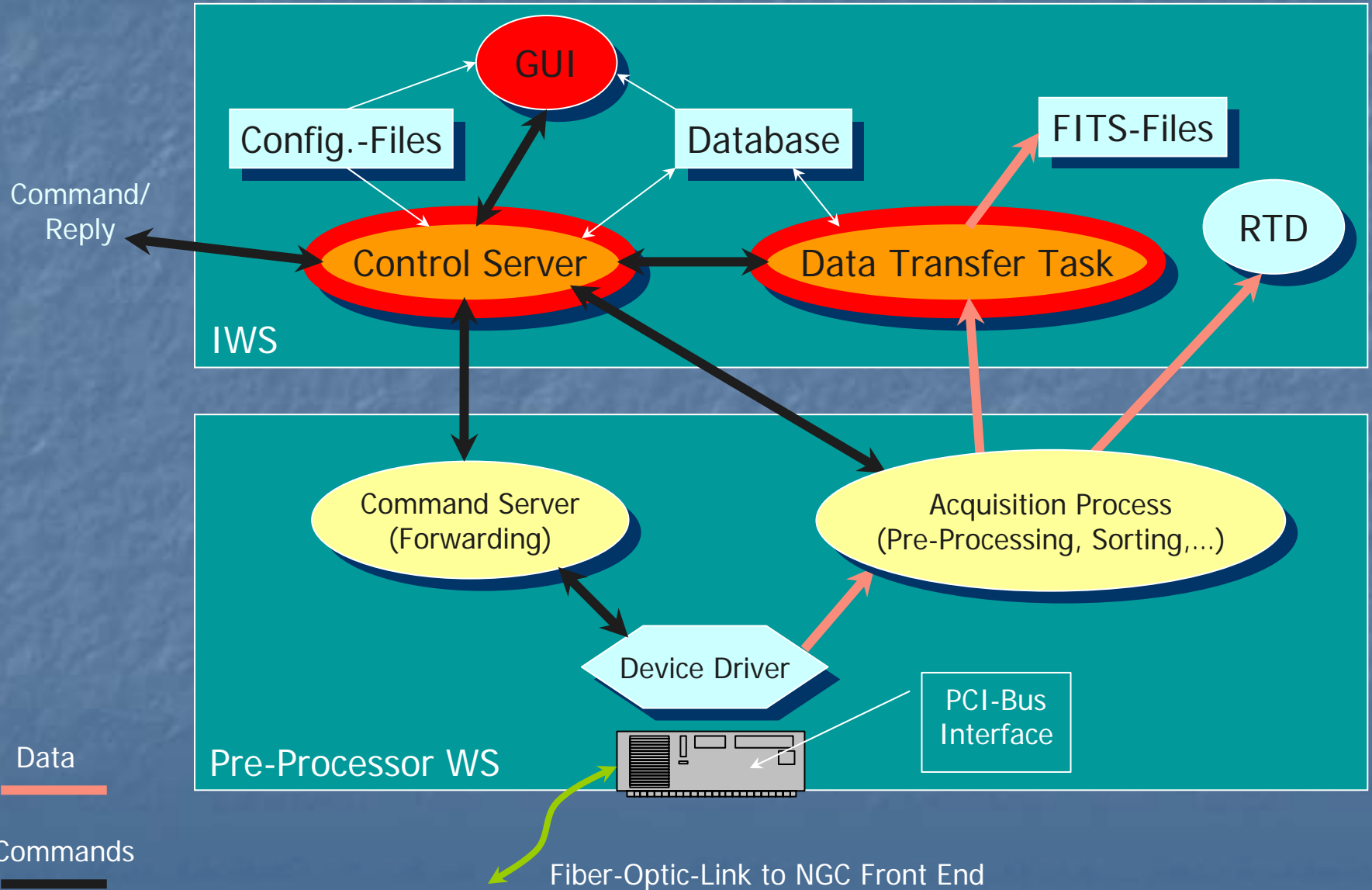
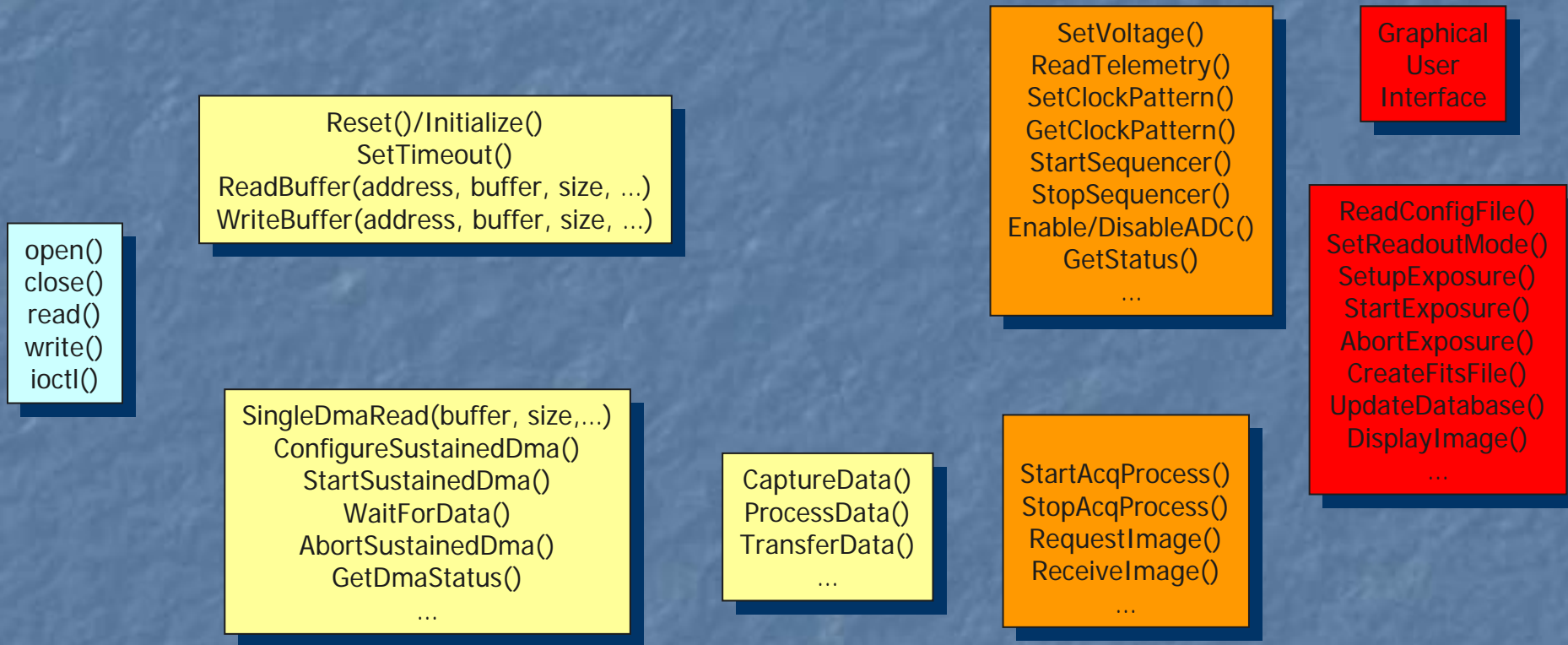


NGC - DCS Processes



Software Layers



Driver-Level

Driver Interface
Libraries

Acquisition
Process

Controller
Interface

High Level DCS

Driver and Interface

- Device driver for RH Linux 2.4.20 is ready (module "ngcdrv").
- **Driver Interface Libraries** hide changes in HW and operating system (LINUX kernel) and make the SW transparent to the next SW layer. They are part of the **NGC Base Software**, which also contains some other functionality (such as a transparent threads interface, priority control, etc.) and a **Simulator** for the NGC HW (module "ngcb" – under testing).

Acquisition Process

- The pre-processing framework for the multi-threaded **Acquisition Process** has been taken over from IRACE (module "ngcpp" – under testing).
- Currently this is required only for pre-processing in IR applications.
- Template processes have been developed, which are an easy-to-use and stand-alone tool to visualize NGC-Data on the RTD.

Controller Interface

- The **Controller Interface** provides modular objects for **Sequencer-**, **CLDC-** and **ADC-Control** and an object for interfacing to the **Acquisition Process** and for the **Asynchronous Data Reception**.
- The objects can be assembled in a server in an arbitrary way to reflect all functionality of any NGC hardware configuration (multiple instances of **Sequencer-**, **CLDC-**, **ADC-modules** and any number of **Acquisition Processes**).
- Configuration file formats for **Clock-Patterns**, **Voltage-Setup** and a **Sequencer Programming Language** are defined.
- A simple interactive example server has been created, which uses these objects in a default configuration to allow hardware development and detector tests.
- Module name TBD ("ngci", "ngcdcs", ... ?).